

# Windows SDK sample overview(en)

## General

This directory contains document of slamware demo programs, which are developed based on Slamware windows SDK

**KBSW180136 Win32 - Navigate to Target PointStandard Mode and Virtual Track Mode**

**KBSW180137 Win32- Recover Localization**

**KBSW180140 Win32- Virtual Wall/Virtual Track Operation( Add, Delete, Modify**

**KBSW180141 Win-32- Save and Load Composite Map**

**KBSW190925 Win32 - Rotate a particular angle/Rotate to a particular angle**

**KBSW190926 Win32 - Go back to charge**

**KBSW190927 Win32 - Get the data of sensors**

**KBSW191008 Win32 - Get the battery percentage and power status**

**KBSW191009 Win32 - Get the original data of laser scanning**

**KBSW191010 Win32 - Speed Regulation**

**KBSW191011 Win32 - Configure the network of robot**

**KBSW191012 Win32 - Virtual Track with OA Navigation**

**KBSW191014 Win32-Robot's health**

## Recently Updated

### Recently Updated

As you and your team create content this area will fill up and display the latest updates.