

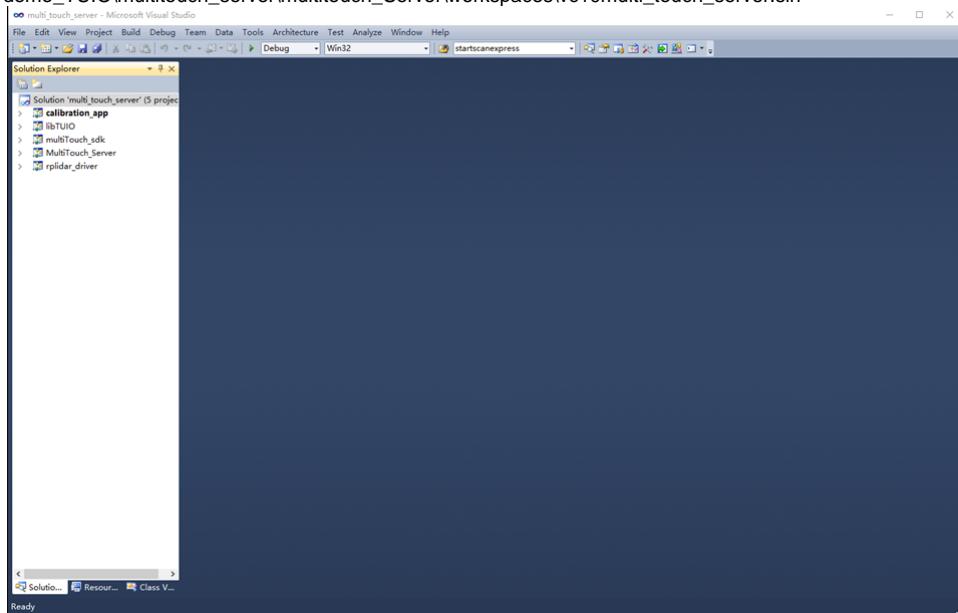
KBLD183003 RPLiDAR

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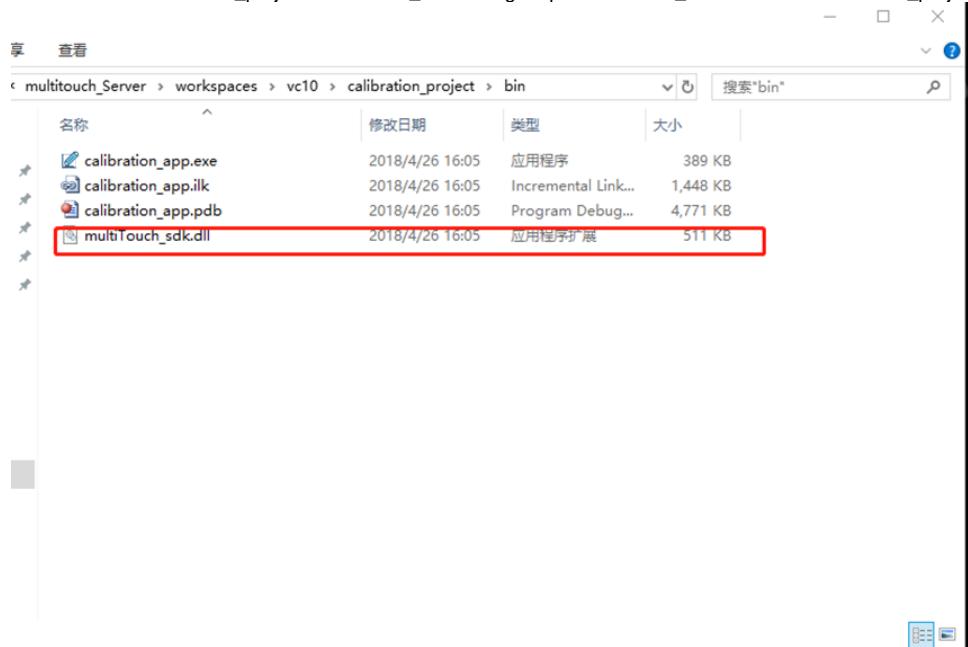
: <https://pan.baidu.com/s/1sJn9BTAYEqMLxU8daHJvxg> : nuwk

RPLiDAR A1SDKVS 2010

1. demo_TUIO\multitouch_server\multitouch_Server\workspaces\vc10multi_touch_server.sln

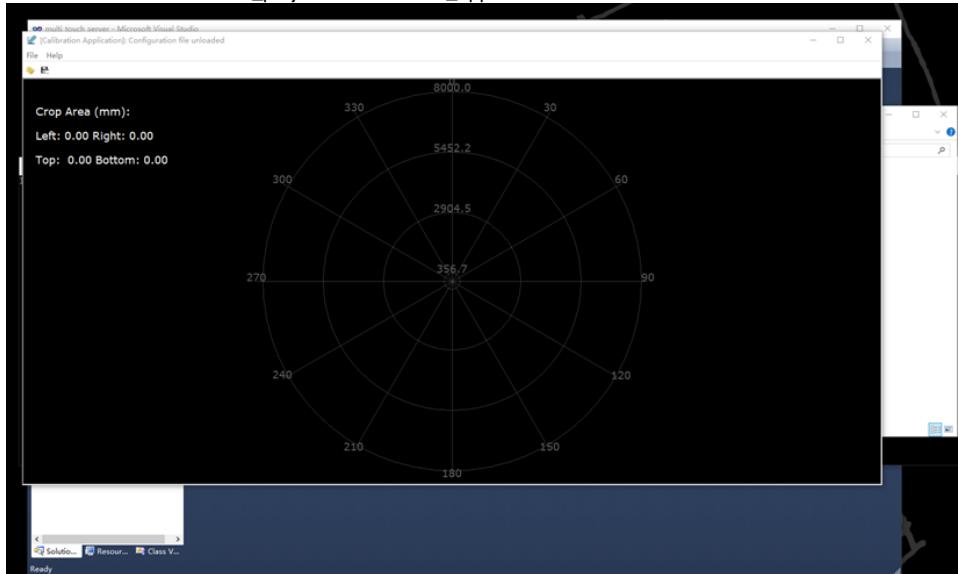


2. Rebuild resolution. ...\\sdk_project\\multiTouch_sdk\\Debug\\outputmultiTouch_sdk.dll...\\vc10\\calibration_project\\bin...\\server_project\\bin.

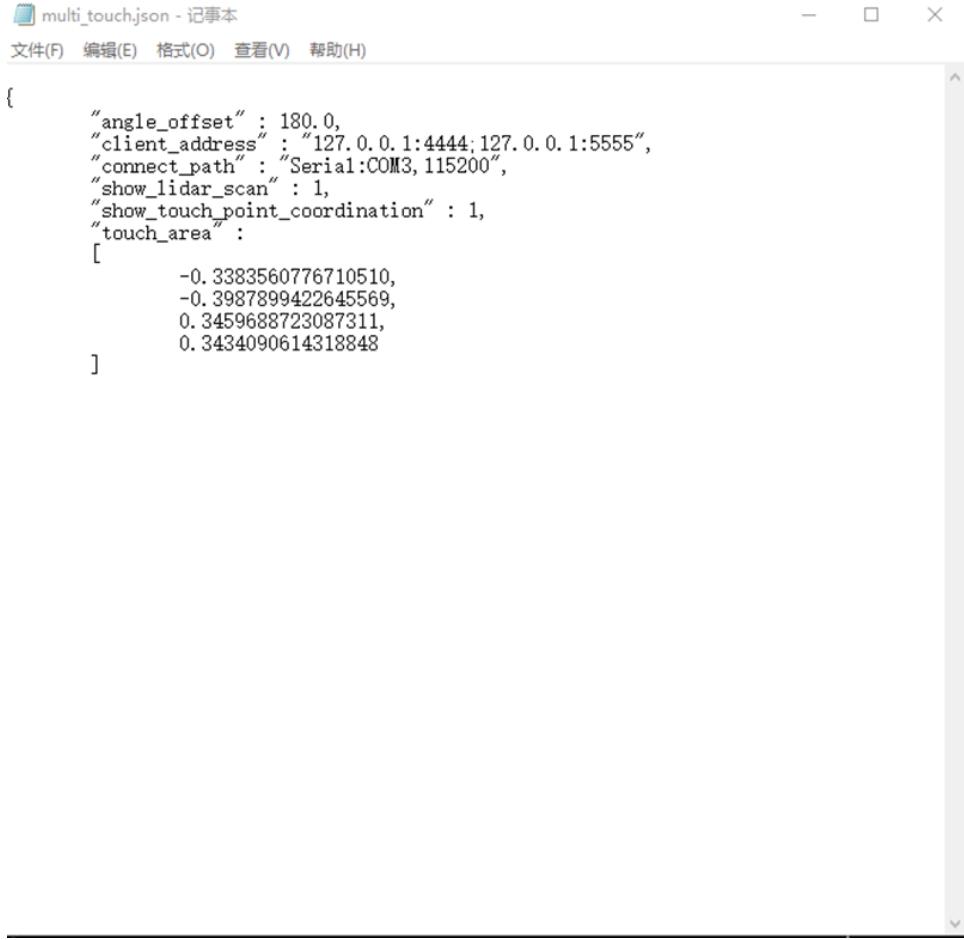


dllmultiTouch SDK

3. RPLiDAR...\\vc10\\calibration_project\\bin\\calibration_app.exe



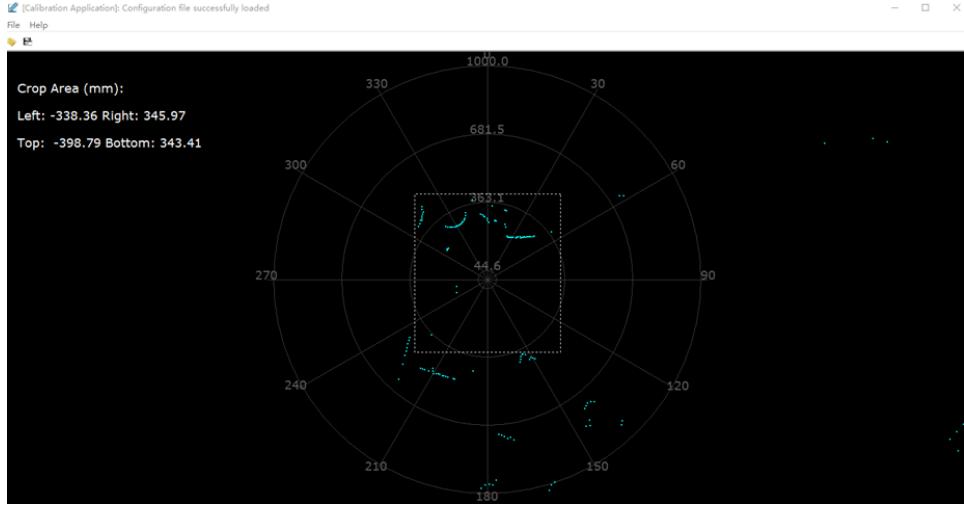
4. load configuration...\\vc10\\server_projectmulti_touch.jsonclientipTouch area



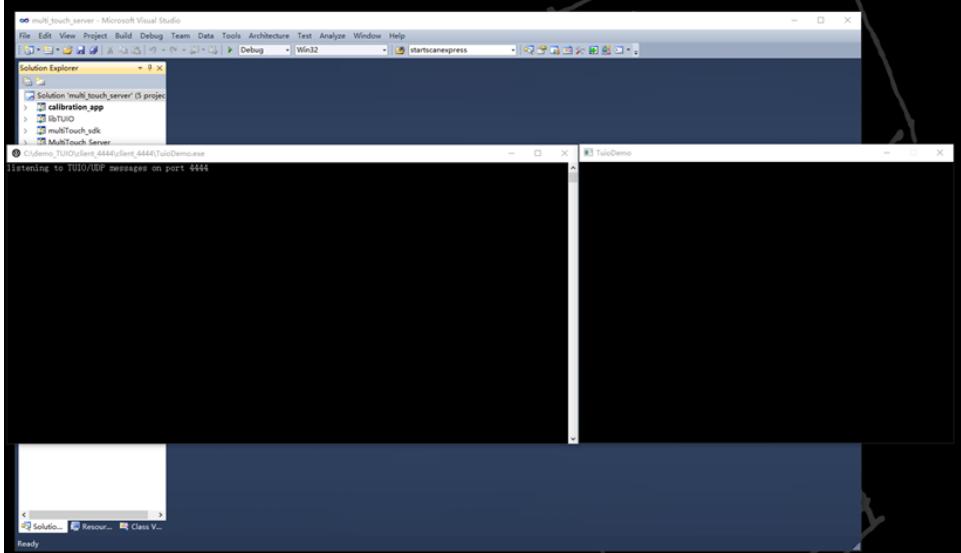
The screenshot shows a Windows Notepad window titled "multi_touch.json - 记事本". The file contains JSON configuration code for a touch area. The code includes settings for angle offset, client address, connect path, lidar scan, touch point coordination, and a list of touch coordinates.

```
{  
    "angle_offset" : 180.0,  
    "client_address" : "127.0.0.1:4444;127.0.0.1:5555",  
    "connect_path" : "Serial:COM3, 115200",  
    "show_lidar_scan" : 1,  
    "show_touch_point_coordination" : 1,  
    "touch_area" :  
    [  
        -0.3383560776710510,  
        -0.3987899422645569,  
        0.3459688723087311,  
        0.3434090614318848  
    ]  
}
```

5. calibration_appTouch Area

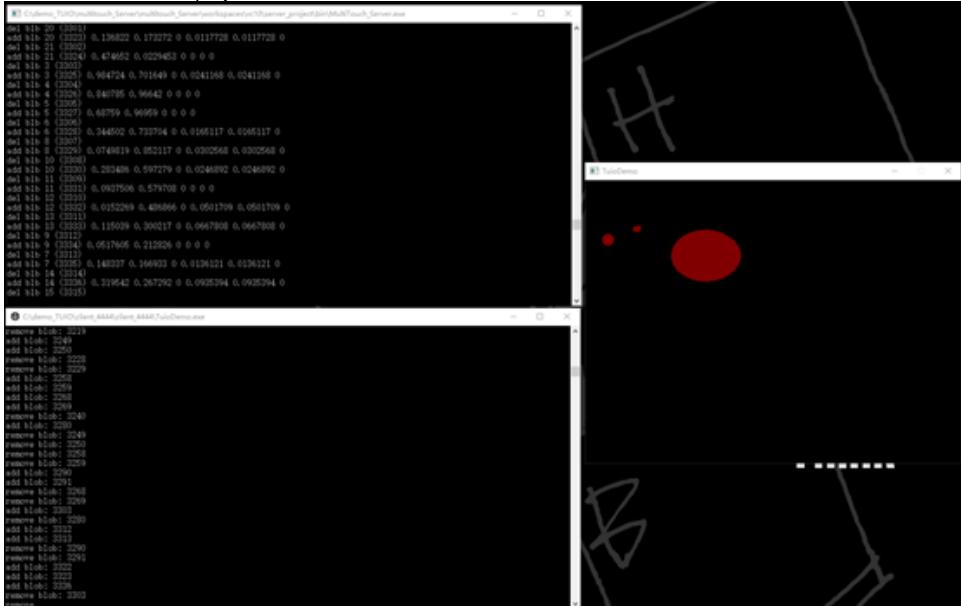


6. save configuration calibration_appclient_4444TuioDemo.exe console server console client add Blob remove Blob Blob



client_44444444

7. server...vc10\server_project\binMultiTouch_Server.exe. client server console add remove blob



demo_TUIO.MOV