

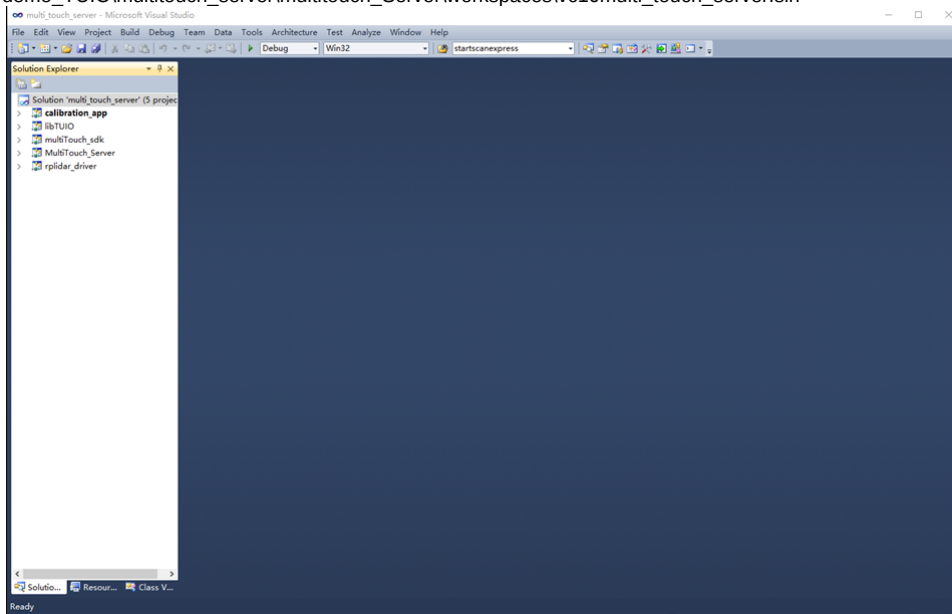
KBLD183003 RPLiDAR

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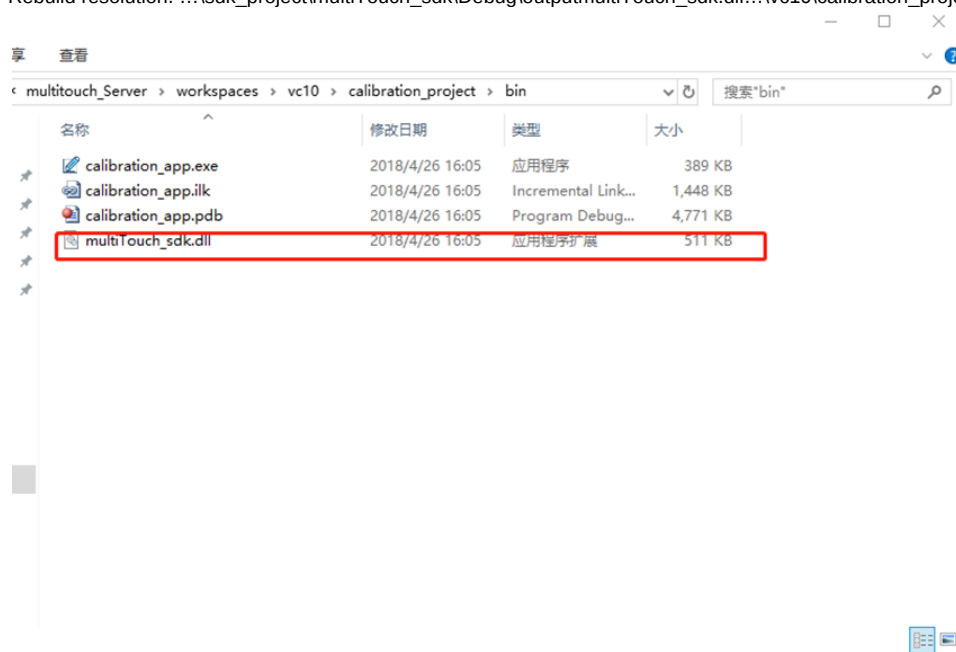
: <https://pan.baidu.com/s/1sJn9BTAYEqMLxU8daHJvxg> : nuwk

RPLiDAR A1SDKVS 2010

1. demo_TUIO\multitouch_server\multitouch_Server\workspaces\vc10multi_touch_server.sin

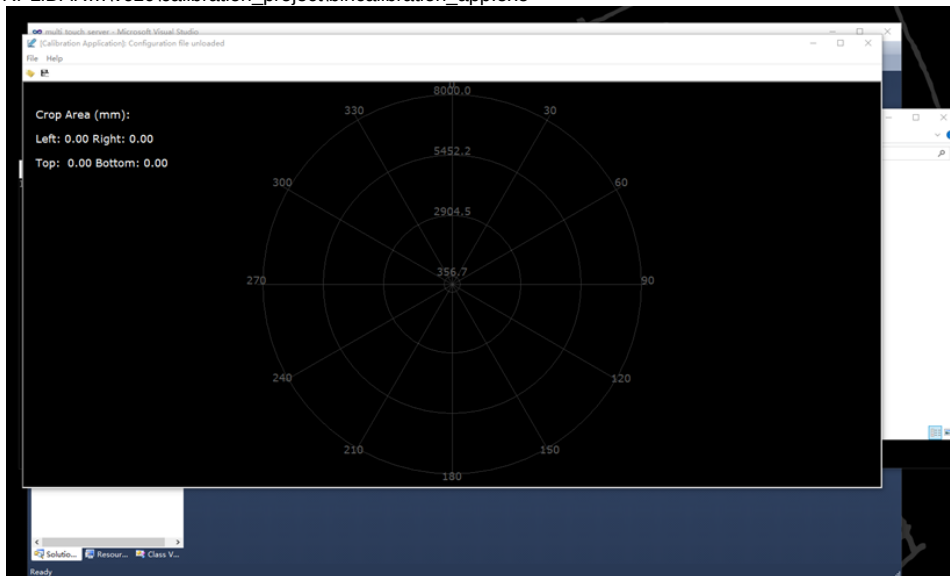


2. Rebuild resolution. ...\\sdk_project\\multiTouch_sdk\\Debug\\outputmultiTouch_sdk.dll...\\vc10\\calibration_project\\bin...\\server_project\\bin.



dllmultiTouch SDK

3. RPLIDAR...\\vc10\\calibration_project\\bin\\calibration_app.exe

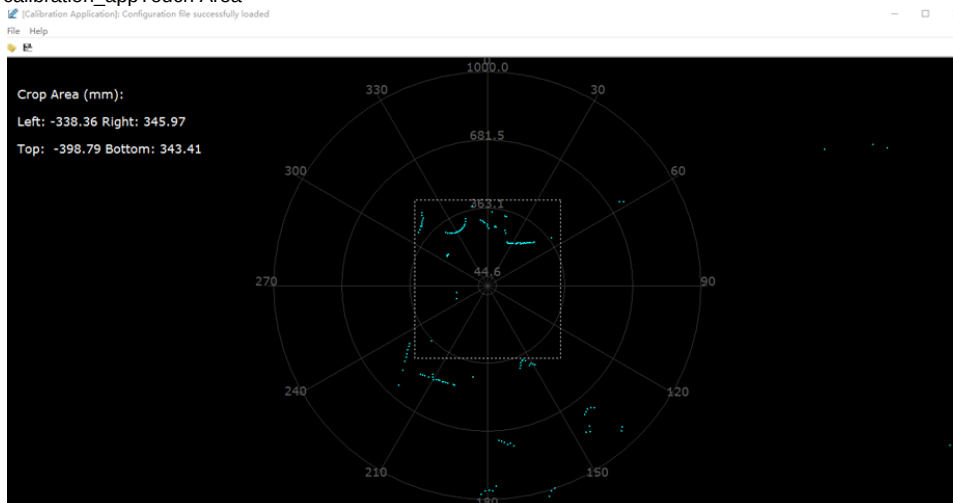


4. load configuration...\vc10\server_projectmulti_touch.jsonclientipTouch area

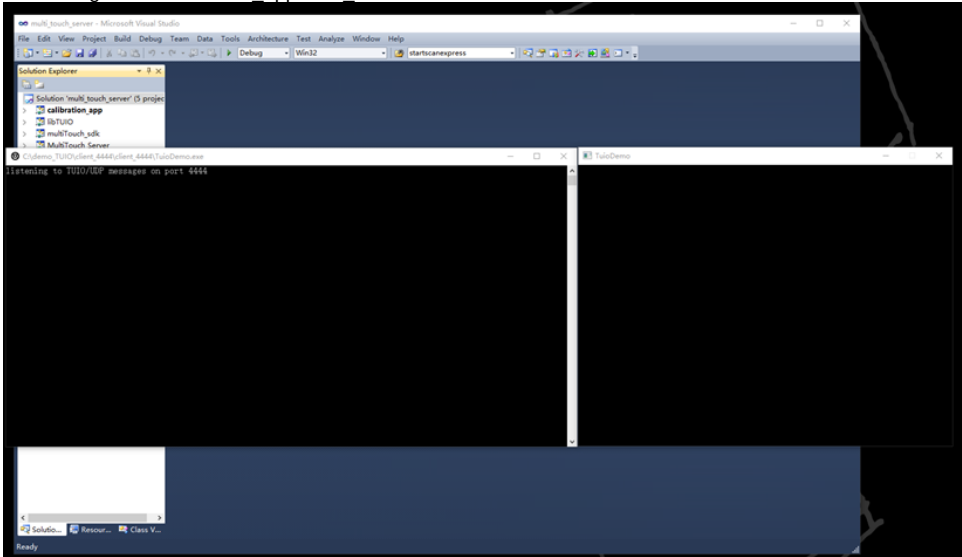
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multi_touch.json - 记事本
文件(F) 编辑(E) 格式(O) 查看(V) 帮助(H)

{
  "angle_offset" : 180.0,
  "client_address" : "127.0.0.1:4444;127.0.0.1:5555",
  "connect_path" : "Serial:COM3,115200",
  "show_lidar_scan" : 1,
  "show_touch_point_coordination" : 1,
  "touch_area" :
  [
    -0.3383560776710510,
    -0.3987899422645569,
    0.3459688723087311,
    0.3434090614318848
  ]
}
```

5. calibration_appTouch Area

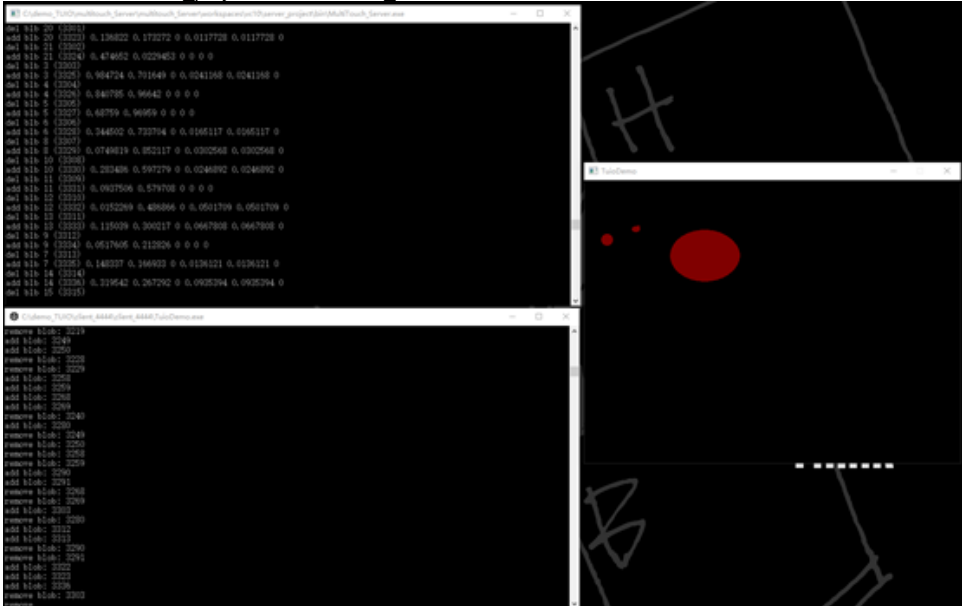


6. save configurationcalibration_appclient_4444TuioDemo.execonsoleserverconsoleclientaddBlobremoveBlobBlob



client_44444444

7. server...\\vc10\\server_project\\binMultiTouch_Server.exe. clientserverconsoleaddremove blob



demo_TUIO.MOV