

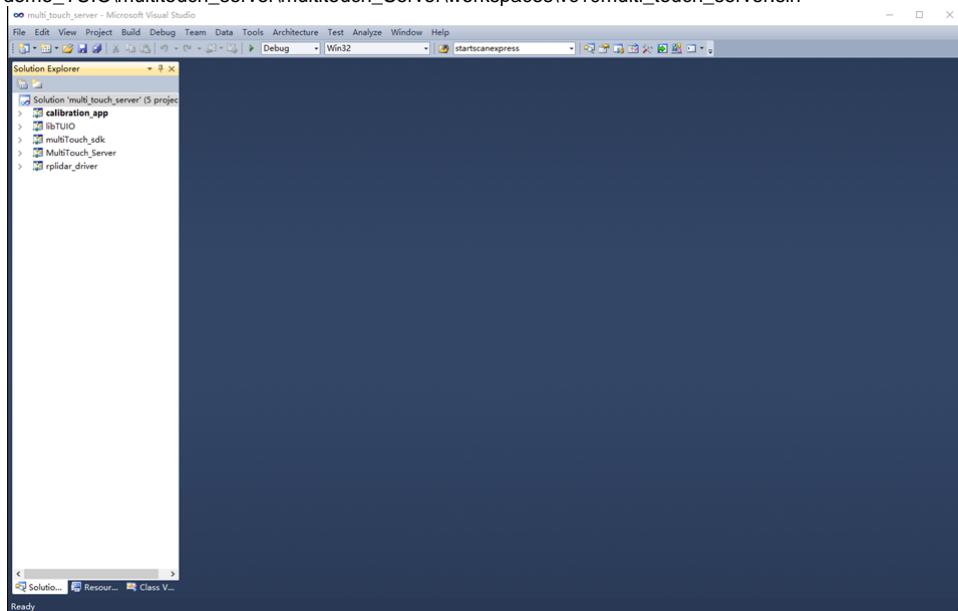
# KBLD183003 RPLiDAR

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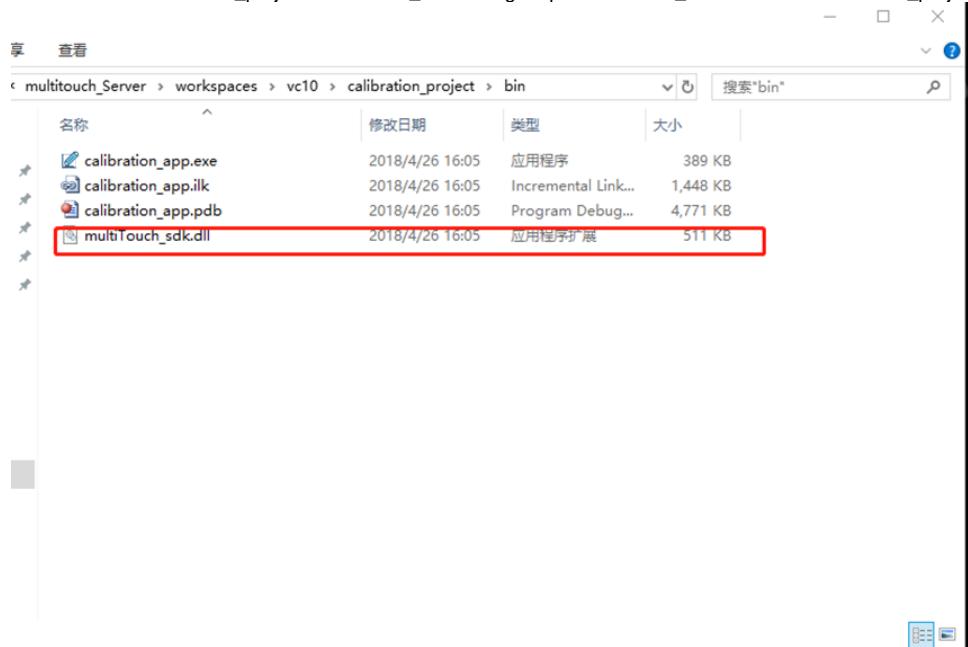
: <https://pan.baidu.com/s/1sJn9BTAYEqMLxU8daHJvxg> : nuwk

RPLiDAR A1SDKVS 2010

1. demo\_TUIO\multitouch\_server\multitouch\_Server\workspaces\vc10multi\_touch\_server.sln

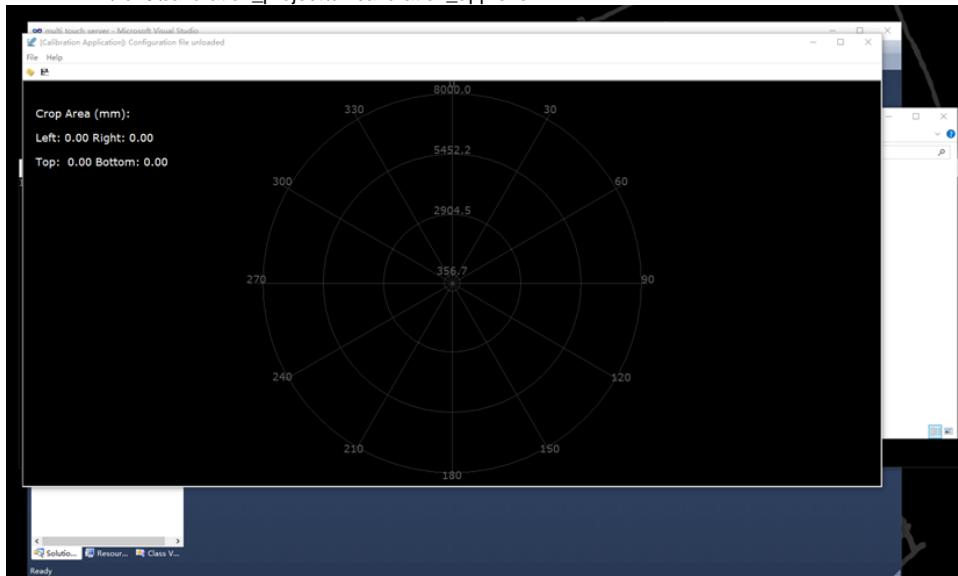


2. Rebuild resolution. ...\\sdk\_project\\multiTouch\_sdk\\Debug\\outputmultiTouch\_sdk.dll...\\vc10\\calibration\_project\\bin...\\server\_project\\bin.

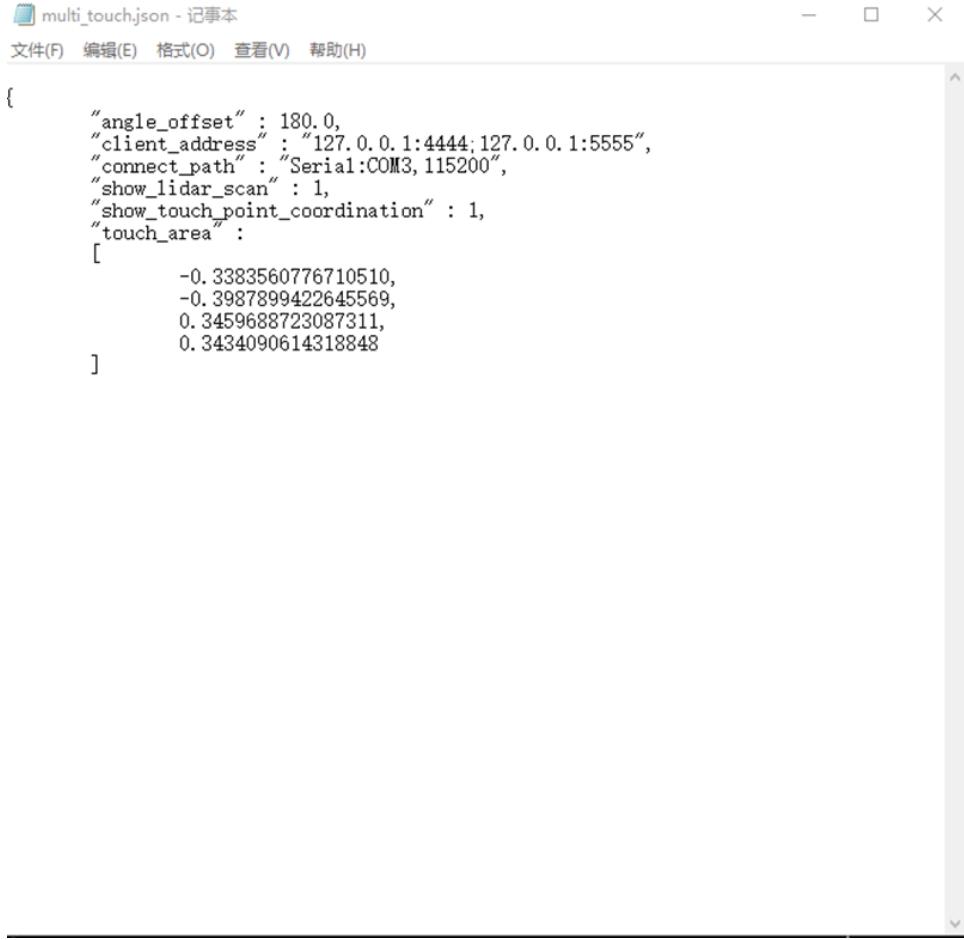


dllmultiTouch SDK

3. RPLiDAR...\\vc10\\calibration\_project\\bin\\calibration\_app.exe



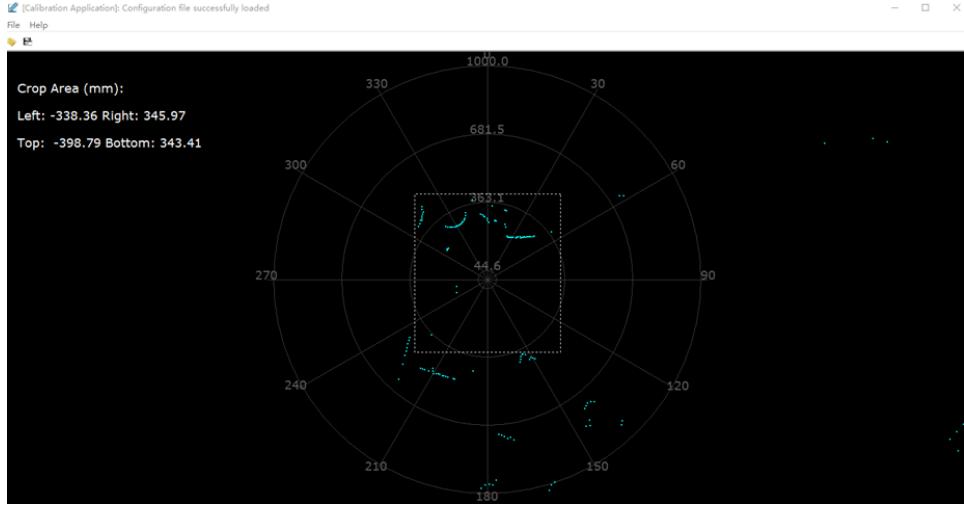
4. load configuration...\\vc10\\server\_projectmulti\_touch.jsonclientipTouch area



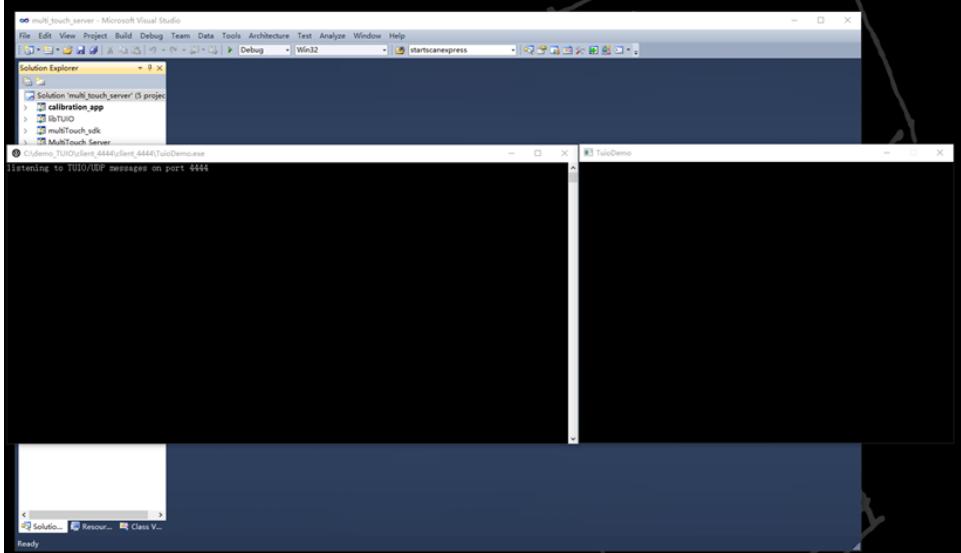
The screenshot shows a Windows Notepad window titled "multi\_touch.json - 记事本". The file contains JSON configuration code for a touch area. The code includes settings for angle offset, client address, connect path, lidar scan, touch point coordination, and a list of touch coordinates.

```
{  
    "angle_offset" : 180.0,  
    "client_address" : "127.0.0.1:4444;127.0.0.1:5555",  
    "connect_path" : "Serial:COM3, 115200",  
    "show_lidar_scan" : 1,  
    "show_touch_point_coordination" : 1,  
    "touch_area" :  
    [  
        -0.3383560776710510,  
        -0.3987899422645569,  
        0.3459688723087311,  
        0.3434090614318848  
    ]  
}
```

5. calibration\_appTouch Area

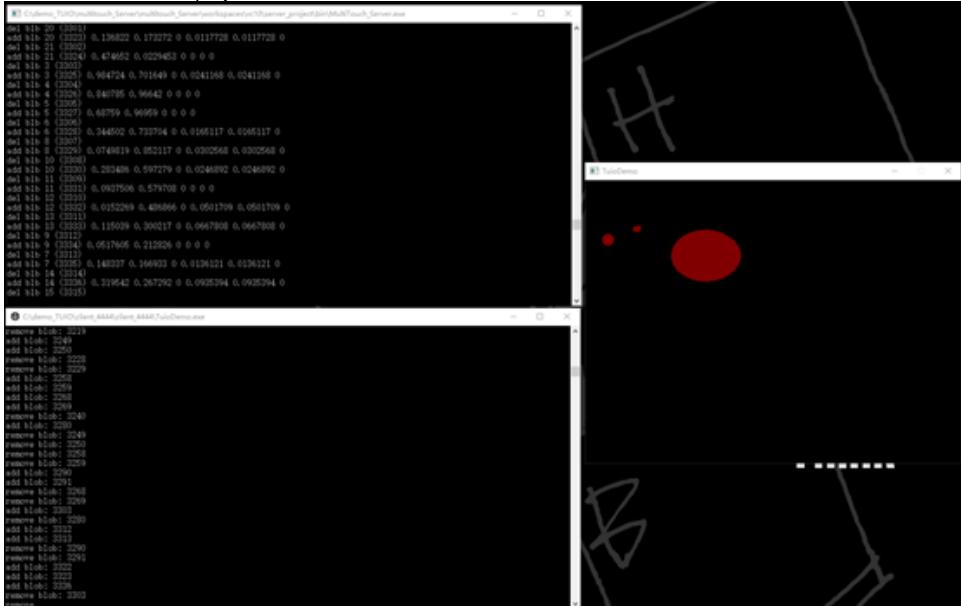


6. save configuration calibration\_appclient\_4444TuioDemo.exe console server console client add Blob remove Blob Blob



client\_44444444

7. server...vc10\server\_project\binMultiTouch\_Server.exe. client server console add remove blob



demo\_TUIO.MOV