

Athena General Robot Platform

Product Selection Guide

Low cost

Small robot development platform

Rich configuration and high scalability



Introduction

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Athena is a small-sized and low cost robot development platform designed by SLAMTEC. It meets small robot application development requirements like intelligent patrol robot and delivery robot and etc.

With build-in SLAMWARE Cube autonomous localization and navigation suite, it is ideal to finish path finding, localization and navigation tasks and come with different applications to work in various commercial environment

Athena adopts multi-sensor fusion technology integrating lidar, ultrasonic sensor, cliff sensor, magnetic sensor, depth camera, bumper, which makes it to have an excellent mapping, localization and navigation performance in complicated and changing environment.

Performance & Parameters

Robot Name			Athena General Purpose Robot Platform					
Robot Version			Professional Standard		Wholesale			
ID								
Core Feature			SLAM localization and navigation	SLAM localization and navigation	SLAM localization and navigation			
Hardware System			SLAMCUBE (K1M1)	SLAMCUBE (K2M1)	SLAMCUBE (K2M1)			
VSLAM			Optional (*Note 1)	None (* Note 1)	None			
Wheel Type			Two wheel differential driving	Two wheel differential driving	Two wheel differential driving			
Mass & Volume	Dimension		406mm*384mm*303mm (±10mm)	406mm*384mm*288mm (±10mm)	406mm*384mm*231mm (±10mm)			
	Weight		About 30kg	About 29kg	About 20kg			
	Top Weight		About 30kg	About 30kg	About 30kg			
Mapping	Map definition		5cm	5cm	5cm			
Performance	Maximum Mar	oping Area	500m *500m	350m *350m	350m *350m			
		Ethernet	10/100/1000 Mbps	10/100/1000 Mbps	10/100/1000 Mbps			
		User Power	DC 20~25.2V 5A Max	DC 20~25.2V 5A Max	DC 20~25.2V 5A Max			
	Hardware Interface	System Switch	Yes (*Note 1)	Yes				
Heor		Emergency Stop	Yes	Yes	Self-defined 15 pin interface			
User interface		Brake Release	Yes	Yes				
IIIteriace		Turn Light	Yes	Yes	None			
		Wi-Fi	5G&2.4G	5G&2.4G	5G&2.4G			
			802.11a/b/g/n/ac	802.11a/b/g/n/ac 802.11a/b/g/n/ac 802.11a/b/g/				
	Software	SLAMWARE™	Windows/iOS/Android/Linux	Windows/iOS/Android/Linux	Windows/iOS/Android/Linux			
Walking Performance	Walking Speed		0~1m/s	0~1m/s	0~1m/s			
	Maximum Passing Slope		5°	5°	5°			
	Maximum Passing Obstacle Height		20mm	20mm	20mm			
	Maximum Passing Gap Width		40mm	40mm	40mm			
Sensor Performance	Rplidar Scan Radius		40m	25m	25m			
	Single Hole	Number	1	1	1			
	Type USS	FOV	60°	60°	60°			

		Maximum Detecting					
	Distance		45cm		45cm		45cm
	Standard USS	Number	2		2		2
		FOV	15°		15°		15°
	Standard 033	Maximum Detecting Distance	45cm		45cm		45cm
	Multi-cliff	Number	1		1		1
	Sensor Minimum Detecting Distance		5cm		5cm		5cm
	Magnetic Sensor	Number	2		2		2
		Number	1 0.3m~3m H67.9° V45.3°		Extension supported (*Note 1)		Extension supported
		Detecting Distance					
	Depth Camera	Range					
		Field of View(FOV)					
		USB Port	2.0				
	Mechanical Bumper	Number	2		2		2
		Minimum Trigger Stress	8N		8N		8N
Battery	Capacity & Specification		24V16AH		24V16AH		24V10AH
	Power Dissipation In Stand-by Time		<20W		<20W		<20W
	Working Hours		< = 4.5h		< = 4.5h		< = 3h
			(walking constantly after fully charged)		(walking constantly after fully charged)		(walking constantly after fully charged)
	Maximum Walking Distance		<=8 KM (0.5m/s constantly)		<=8 KM (0.5m/s constantly)		<=5 KM (0.5m/s constantly)
Autonomous Recharging	Charging Station Output		24V6A		24V6A		— Optional
	Charging Time		< = 3h		< = 3h		
	Quick Charging Station Output		24V10A	24V10A Optional	24V10A	- Optional	无
	Charging Time		< = 1h	< = 1h	Ориона		
Operating	Operating Temp	erature	0°~40°		0°~40°		0°~40°
Environment	t Operating Humidity		30%~70% 30%~70%			30%~70%	
			-				

*Note 1:

Optional: the product supports to specific configuration which is not included in the normal delivery.

Yes: Product delivery included.

None: Product delivery not included or product not supported.

Extension supported: the product supports to receive depth camera data via SDK interfaces.