

Windows SDK sample overview(en)

General

This directory contains document of slamware demo programs, which are developed based on Slamware windows SDK

[KBSW180136 Win32 - Navigate to Target PointStandard Mode and Virtual Track Mode](#)

[KBSW180137 Win32- Recover Localization](#)

[KBSW180140 Win32- Virtual Wall/Virtual Track Operation\(Add, Delete, Modify](#)

[KBSW180141 Win-32- Save and Load Composite Map](#)

[KBSW190925 Win32 - Rotate a particular angle/Rotate to a particular angle](#)

[KBSW190926 Win32 - Go back to charge](#)

[KBSW190927 Win32 - Get the data of sensors](#)

[KBSW191008 Win32 - Get the battery percentage and power status](#)

[KBSW191009 Win32 - Get the original data of laser scanning](#)

[KBSW191010 Win32 - Speed Regulation](#)

[KBSW191011 Win32 - Configure the network of robot](#)

[KBSW191012 Win32 - Virtual Track with OA Navigation](#)

[KBSW191014 Win32-Robot's health](#)

Recently Updated

Recently Updated

As you and your team create content this area will fill up and display the latest updates.